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More Complex Gates

 $F = \overline{AB + CD} \implies N_{tree}$ will provide 0's, P_{tree} will provide 1's

0's of function F is \overline{F} , $\Rightarrow \overline{F} = \overline{\overline{AB + CD}} = AB + CD$

nMOS transistors need high true inputs, so it is desirable for all input variables to be high true, just as above.



Likewise, a Ptree will provide 1's.

 $F = \overline{AB + CD}$, need a form involving \overline{A} , \overline{B} , \overline{C} , \overline{D}

Apply DeMorgan's Theorem:

$$F = \overline{AB} \cdot \overline{CD} = (\overline{A} + \overline{B}) \cdot (\overline{C} + \overline{D})$$

Implementation \Rightarrow



AB

Can also use K-maps:

$F = \overline{AB + CD}$	CD	1	1	0	1
		1	1	0	1
		0	0	0	0
		1	1	0	1

For N_{tree}, minimize 0's; for P_{tree}, minimize 1's



 $N_{tree} = AB + CD$



$$P_{\text{tree}} = \overline{A} \cdot \overline{C} + \overline{A} \cdot \overline{D} + \overline{B} \cdot \overline{C} + \overline{B} \cdot \overline{D}$$
$$= \overline{A} (\overline{C} + \overline{D}) + \overline{B} (\overline{C} + \overline{D})$$
$$= (\overline{A} + \overline{B}) \cdot (\overline{C} + \overline{D})$$

Tri State Inverter



EN	Ι	0
0	X	Ζ
1	0	1
1	1	0

"Z" is high impedance state

Implementation? Here is one method:



Alternate representations:



or



where the connection for \overline{EN} is understood or implied, \overline{EN} still needs to somehow be provided in the physical circuit

Transmission Pass Gate Logic



Will require

(4 transistors for two pass gates) + (2 transistors for inversion of S) = 6 transistors total

This technique uses less transistors than a design using normal gates, but is <u>non-restoring</u>. Pass gate logic has no drive capability. Drive comes from orginal A, B inputs.

A D-Latch using transmission gates:



Recall flip-flop construction from CAD course (edge triggered device) —

 \rightarrow two latches in a master-slave arrangement are required



How would a D-Latch with an asynchronous reset be implemented?



Note: when connected to inverted terminal of transmission gate, then the inverter is implied

Introduction to Static Load Inverters





When I = 1, inverter dissipates static power.

Switching point of inverter depends on ratio of R to R_{ON} (on resistance of *n*MOS device.

 $V_{OH} = 5V$, $V_{OL} \approx 0V$, depends on ratio of R/R_{on}

Note: output can swing from 0V to 5V (Vdd)

2)



Note: output swings from ≈ 0 V to (Vdd - V_{Tn})

Using a transistor as a load tends to require <u>much less</u> silicon area than a resistor.

 $V_{OH} = Vdd - V_{Tn}$, $V_{OL} \approx 0V$, depending on ratio of R_{ON} of two enhancement devices Depletion-mode *n*MOS



*n*MOS device with $V_{Tn} < 0V$ (negative threshold voltage). Device is always conducting if $V_{GS} > 0V$.

3)



 $V_{OH} = 5V$; $V_{OL} \approx 0V$, depending on ratio of $R_{ON,dep}$ to $R_{ON,enh}$.

Depletion-mode devices were used before it was economical to put both p-type and n-type devices on the same die.

4) pMOS device as static load



Here also the load device is <u>always</u> on (conducting).

Dissipates static power when I = 1.

 $V_{OH} = 5V$; $V_{OL} \approx 0V$, depending on ratio of $R_{ON,p}$ to $R_{ON,n}$

Basic MOS Device Equations



The *n*MOS device is a *four* terminal device: Gate, Drain, Source, Bulk.

Bulk (substrate) terminal is normally ignored at schematic level, usually tied to ground for the nMOS case. In analog applications, however, the bulk terminal may not be ignored.

Gate controls channel formation for conduction between Drain and Source. Drain at higher potential than Source — Source usually tied to GND to act as pull-down (nMOS).

Three regions of operations — first-order (*ideal*) equations:

Cutoff region

$$I_D = 0A$$
 $V_{GS} \le V_{Tn}$ (*n*MOS threshold voltage)

Linear region

$$I_{D} = \beta \left((V_{GS} - V_{Tn}) V_{DS} - \frac{V_{DS}^{2}}{2} \right) \qquad 0 < V_{DS} < V_{GS} - V_{Tn}$$

Note: I_D is linear with respect to (V_{GS} - V_{Tn}) only when $\frac{V_{DS}^2}{2}$ is small.

Saturation region

$$I_{D} = \frac{\beta}{2} \left(V_{GS} - V_{Tn} \right)^{2} \qquad \qquad 0 < V_{GS} - V_{Tn} < V_{DS}$$

Device parameters:

 β = transistor gain factor, dependent on process parameters and device geometry

process dependent, constant

$$\beta = \left(\frac{\mu\epsilon}{t_{ox}}\right) \left(\frac{W}{L}\right)$$

under control of the designer

As W/L increases, effective R_{ON} of device <u>decreases</u>

 μ = surface mobility of the carriers in the channel

 ε = permittivity of the gate insulator

 t_{ox} = thickness of the gate insulator

See Figure 2.5, 2.8 concerning μ , ϵ , and t_{ox}

SPICE represents β by a factor given by

$$\mathbf{K}' = \boldsymbol{\mu} \mathbf{C}_{\mathrm{ox}} = \boldsymbol{\mu} \, \frac{\boldsymbol{\epsilon}}{\mathbf{t}_{\mathrm{ox}}} = \mathbf{K} \mathbf{P}$$

So,

$$I_{D} = \frac{K'}{2} \frac{W}{L} (V_{GS} - V_{Tn})^{2}; \qquad \text{saturation region}$$

VI characteristic



Things to note:

In the "linear" region, I_D becomes less and less linear with V_{GS} as V_{DS} becomes large. This is because the $\frac{V_{DS}^2}{2}$ term in the linear region grows large.

Higher V_{GS} values increase channel conductance allowing for higher values of I_D for a given V_{DS} .

Predicting I_D values with ideal equations

In saturation region,

$$I_{\rm D} = K' \left(\frac{W}{L}\right) \frac{(V_{\rm GS} - V_{\rm T})^2}{2}$$

If we have



then we can calculate I_D based on $V_{in},\,K^\prime,\,V_T$ (MOSFET parameters).

In specifying W, L values, these are often given in a <u>dimensionless</u> unit called <u>lambda</u>.

When mapping the transistor schematic/layout to a particular technology, the actual W, L will be calculated as:

W' (actual, microns (μ))= W × lambda (microns)L' (actual, microns)= L × lambda (microns)

So lambda is a scaling factor. Note that the ratio $\frac{W}{L}$ is what is important, and that

$$\frac{W'}{L'} = \frac{W \times lambda}{L \times lambda} = \frac{W}{L} .$$

Scaling factor lambda allows transistor $\frac{W}{L}$ values specified in schematics to be technology independent.

For MOSIS foundry vendors, 2.0μ technology \Rightarrow lambda = 1.0 1.2μ technology \Rightarrow lambda = 0.6 0.8μ technology \Rightarrow lambda = 0.4.

Note, however, that lambda *is not* always $\frac{1}{2}$ technology miniumum feature size (line width). Scaling factor lambda *is* foundry/silicon vendor dependent.

In schematic, $\frac{V_{DD}}{L} \Rightarrow$ $\frac{W}{L} = \frac{18}{2} \Rightarrow$ $\frac{W}{L} = \frac{10.8\mu}{1.2\mu}$ $\frac{W}{L} = \frac{10.8\mu}{1.2\mu}$

*n*MOSFET layout:



In digital logic, typically will draw all transistors with the <u>minimum</u> gate length $(= 2 \times \text{lambda})$ and <u>vary the width</u>.

Larger W \Rightarrow larger transconductance (more current flow for given gate voltage), higher gate capacitance

During fabrication process, the actual width and length of the channel can be *reduced* by diffusion from the bulk, source, and drain into the device channel.

SPICE has some MOSFET model parameters to account for this effect, LD and WD, where the actual the actual length and width is calculated as

 $L_{effective} = L_{drawn} - 2 \times LD$

 $W_{effective} = W_{drawn} - 2 \times WD$

If LD, WD parameters not specified in the model, then SPICE assumes they are 0.