PAL Programmable Logic Devices.

Consider implementing a general Boolean function of two variables A and B. This can be expressed as a sum of product terms.

The device shown in figure produces all possible (2^2) product terms formed by two variables. The inputs entered into the logic sum are selected by programmable fuses. Such devices are collectively termed as Programmable Logical Devices or PLDs.



Figure 1

Example: X = A.B + A'.B' requires that fuses f1 and f4 to be "blown".

The above PLD has "fixed" AND gates and a "programmable" OR gate. If we wanted to implement m different functions, each having n inputs we would need a similar PLD with n inputs and m outputs. Inside the chip we would have 2^n AND gates and m OR gates. Each OR gate would have 2^n inputs, so the PLD would have to have a m x 2^{n+1} matrix of programmable fuses.



Figure 2 Simplified PROM

A simplified diagram of a 3 input x 2 output chip is shown in figure 2.

The 2 x 8 x 8 = 128 programmable fuses in the OR matrix are located at the intersections of the 16 horizontal with the 8 vertical lines. Each of the first 8 horizontal lines represents a possible minterm entering for the sum of products into the function X and similarly the lines 9 to 16 represent all the possible minterms entering into the sum for the function Y.

The PLD with fixed AND and programmable OR matrices is called PROM (Programmable Read Only Memory). It allows us to store m different truth tables, each having the same number of n variables.

PLDs are particularly useful for storing data. Imagine that we want to store 64 arbitrary 8 digit numbers. If we use a PROM with at least 5 inputs and 8 outputs, then each input combination (there are $2^5 = 64$) gives a different 8 digit number on the output. We can consider any given input combinations as an address in the memory were the eight digit number resides.

PAL (Programmable Array Logic).

Although great for data storage, PROMs are wasteful when used to represent logic functions. Most logic functions contain only a small number of minterms, whereas PROM provides us with all the minterms, whether we need them all not. To implement a particular logic function it is more convenient to have a smaller number of product terms to choose from. But then we need the facility to "program in" those minterms which are actually contained in that function. This can be achieved using a PLD with programmable AND and fixed OR matrices. Such a PLD is known under the acronym PAL.



Figure 3: Structure of PAL

Returning to our example of two logic functions, each having 3 variables, consider how to implement on PAL the following two functions:

X = A.B.C' + A.B.'C + A'.B'.C'Y = A'.B.C + A'.B'.C + A.B.C' + A.B.C The first function requires 3 AND gates and the second four AND gates. Thus we need at least 7 AND gates and two OR gates.

The implementation using a 3 input x 2 output PAL is shown in figure 3.

The programmable AND array consists of six columns and 16 rows. Each intersection of a column and a row represents a programmable fuse. Rather than talking about the fuses we will picture an intersection where the fuse has not "blown" as a link.

Thus there are $6 \ge 16 = 96$ programmable fuses (or links), somewhat smaller number than was needed for PROM.

If we denote a link by (row, column) it connects we see that we need the following links to implement the minterms in function X:

Minterm	Links
A.B.C' ~	(0,0) $(0,2)$ and $(0,5)$
A.B'C ~	(1,0) (1,3) and (1,4)
A'.B'.C' ~	(2,1) $(2,3)$ and $(2,5)$

Similarly for function Y.

Commercial PLDs come in several sizes. PAL chips have been around from early seventies so there is a "de facto" standard. The type of PAL is denoted as

PAL#inputs (designation letter) #outputs .

The most popular sizes are 16 inputs x 8 outputs (e.g. PAL16L8) and 20 inputs x 8 outputs (e.g. PAL20L8).

Consider PAL16L8. It has 16 inputs and 8 outputs. That is a total of 24 pins, adding the two power supply pins, we would expect a 26 pin package. Yet PAL16L8 is housed in a 20 pin package. This is possible because six pins can be configured to act either as outputs or inputs (they are bi-directional).

The figure 4 shows is the PAL shown in figure 3 with a modified pin X capable of providing input or output. The zero row minterm is used to program the tri state OR gate. If the OR gate output is enabled the pin is nominally an output pin, but it can be also used to provide internal feedback to the other OR gate. When the OR gate output is disabled the pin X can be used as an input pin.

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Figure 4: Structure of PAL with a combined input/output pin.

Figure 5 shows a detailed of another PAL modification allowing to programmatically invert the output pin. If the fuse on the input to the XOR is blown then the output of the OR gate will be inverted.



Figure 5: Programmatic selection of inverted output

Programming of PALs.

The programming file for PAL devices includes the so called fuse map and a set of test vectors. The fuse map shows which fuses have to be blown by the device programmer. The fuses that correspond to the nodes in the programming AND matrix are referred to by their "fuse address", i.e. sequentially increasing numbers. The file also contains information on fuses that represent the internal configuration of the device, such as whether any particular OR gate has to have the output inverted or whether any feedback loops are present. The test vectors represent the expected outputs for a set of pre-defined inputs. Test vectors are used by the device programmer to test the PLD after it has been programmed. The format of the programming file has been standardized and is known as a JEDEC (Joint Electron Device Engineering Council) file.

Hardware Description Languages (HDL).

There are several HDLs that can be used to program PALs. The most commonly used are Abel, Verilog, VHDL and CUPL. In order to produce a downloadable JEDEC file, a source file using one of the above mentioned HDLs is compiled by an appropriate HDL compiler. Many PLD manufacturers produce CAD packages incorporating HDL compiler with additional utilities such as schematic capture software and functional and in-time simulation of the design.

Few examples of using the CUPL (Universal Compiler for Programmable Logic) are given below.

	tatements terminate by		
CUPL key wo	ords are not case sens	itive, but the variable names are.	
* * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *	*****	*****
THIS PROGRA	AM DEMONSTRATES HOW CU	PL COMPILES SINGLE GATES	
**********	* * * * * * * * * * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *	****
	GAL 16		
	.—		
	a x 1	20 x Vcc	
	b x 2	19 x xnor	
	x 3	18 x xor	
	x 4	17 x nor	
	x 5	16 x or	
	x 6	15 x nand	
	x 7	14 x and	
	x 8	13 x invb	
	x 9	12 x inva	
	GND x 10	11 x	

Example of CUPL Source for Logic Functions.

/* The device has ten dedicated inputs (pins 1 to 9 and 11), pins 13 through 18 */
/* can be configured either as inputs or outputs. Pins 12 and 19 can be only */
/* outputs. All outputs can be switched into a high impedance by the product */

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<pre>/* by blowing a c /* Note: In this /* The true sourc</pre>	ghth OR gate input. The outputs of all OR gates can be inverted */prresponding internal configuration fuse.example pins 1 and 2 are the inputs and pins 12 to 19 outputs*/e code starts here:*/Header has to be included in every CUPL source file	
Location N Assembly N	opical Devices, Inc.; /* does not matter what you enter here */ one; /* does not matter what you enter here */ one; /* does not matter what you enter here */ SL8a; /* Important info: PAL 16L8 device */	
<pre>/* PIN is a CUPL Pin 1 = a; /* F</pre>	e inputs to build simple gates from two input variables a and b.*/ eeyword which assigns the variable to an IC pin */ econd input variable as pin 1 is dedicated to input */ econd input variable as pin 2 is dedicated as an input*/	
/* That /* impl	the bidirectional pins as outputs active HI levels. */ these pins are outputs is not yet obvious but they are */ citly defined because, as we shall see, they will appear */ the Left HS of logic equations which determine their values. */	/
<pre>Pin 12 = inva; Pin 13 = invb; Pin 14 = and; Pin 15 = nand; Pin 16 = or; Pin 17 = nor; Pin 18 = xor; Pin 19 = xnor;</pre>	/* a' */ /* b' */ /* a.b */ /* (a.b)' */ /* (a+b) */ /* (a⊕b) */ /* (a⊕b) */	
equation statemen	Logic: examples of simple gates expressed in CUPL */ ts using CUPL specific BOOLEAN operators */ is output <= Right hand side is input */	
<pre>inva = !a; invb = !b; and = a & b; nand = !(a & b); or = a # b; nor = !(a # b); xor = a \$ b; xnor = !(a \$ b);</pre>	<pre>/* inverters */ /* and gate */ /* nand gate */ /* or gate */ /* nor gate */ /* exclusive or gate */ /* exclusive nor gate */</pre>	

As a by-product of compilation the WINCUPL compiler also produces a document file providing the information on the way the design is implemented. Below given are few extracts such as the Symbol Table and the Fuse Map appropriate to the above source code with the explanations as appropriate.

			Symbol	Table			
Pin Vari	able				Pterms	Max	Min
Pol Na	ame	Ext	Pin	Туре	Used	Pterms	Level
a			1	V	-	-	-
and			14	V	1	8	1
b			2	V	-	-	-
inva	1		12	V	1	8	1
invk)		13	V	1	8	1
nanc	1		15	V	1	8	1
nor			17	V	2	8	1
or			16	V	2	8	1
xnoi			19	V	2	8	1
xor			18	V	2	8	1

LEGEND: v = variable

Note: Each OR gate of the 18L6 can take of up to 8 product terms (AND gates). The above table shows the utilization of the internal gates.

 								:
Fuse	Plot	(see	the	fuse	map	shown	below)	
 								:

Explanations:

- Each row represents the status of fuses connected to the input of a single AND gate. Thus the number of rows under each pin gives the number of AND gates for each output OR gate. For example PIN #19 has eight rows, i.e. the output NOR gate has eight inputs, one from each of the eight AND gates.
- 2. Each AND gate has to take a pair of direct and inverted inputs, so it has twice as many inputs as there are input pins on the chip. E.G. 16V8 has up to 16 input pins so all AND gates can have up to 32 inputs.
- 3. Each input literal (variable and its inverted value) is represented by a single columns. For the 16L8 there are 16 variables, thus 32 literals and therefore 32 columns. In our case we use only two input variables: a (pin 1) and b(pin 2). The first column represents the literal a, the second column its inverted value a', the third one b and the fourth column b'. The other columns represent the other input pins which are not used in this example.
- 4. The intersections of columns and rows are termed the AND Programming Matrix.
- 5. Each node of this matrix represents a single fuse which connects the literal represented by the corresponding column to the AND gate input represented by the row. A X signifies fuse not blown (that literal is connected to input of the AND gate) and a fuse blown (not connected). So in our example the first row that represents the single AND gate has only the a and b' inputs connected. The second row that represents the second AND gate has only the inputs a' and b connected. The remaining six AND gates connected to output pin 19 NOR gate are not used. Thus there are only two minterm inputs to the OR gate associated with the output pin 19: a.b' , a'.b.
- 6. Each row that starts with an output pin number provides internal configuration for the output "macro cell". In the example below the important data is the polarity of the output, designated by the POL fuse. If the polarity bit fuse is left connected the output polarity of the OR gate is inverted giving an NOR gate. Otherwise it is unaffected. In our example the fuse is intact so the gate at pin 19 will be inverting (NOR gate). The output of this pin will thus be : (a.b' + a'.b)' which is the formula for an inverting exlusive OR (XNOR). Similarly, the output at pin 18 (not inverting as fuse is blown) yields a.b' + a'.b and that is a XOR function.
- The fuses are labelled by sequential numbers known as "fuse addresses". The left hand side column gives the starting address of the first fuse in each row. For example, the AND matrix corresponding to the output pin 19 has fuses

from address 0000 to 00255. In our example only the fuses with addresses 0, 3, 33 and 34 are connected.

 The fuse map information is contained in a JEDEC file which (alongside other data) holds a table of fuse addresses and their state (intact or blown).

Syn 02192 - Ac0 02193 x

		x 02120	
00032 -xx			

		- 02121	

00416 xxxxx	*****	*******	*****
00448 xxxxx	*****	******	*****
00480 xxxxx	*****	*******	*****
Pin #17 020	50 Pol	x 02122	Ac1 x
00512x			
00544 x			
00576 xxxxx	******	*******	*****
00608 xxxxx	******	*******	*****
00640 xxxxx	******	*******	*****
	*****	*******	*****
00704 xxxxx	******	*******	*****

		- 02123	

			XXXXXXXXXXXX
Pin #15 020 01024 x-x		X UZIZ4	Acl x

Pin #14 020			
01280 x-x			
01312 xxxxx			
01344 xxxxx	*****	******	*****
01376 xxxxx			
01408 xxxxx	*****	*******	*****
01440 xxxxx	*****	******	*****
01472 xxxxx	*****	******	*****
01504 xxxxx	*****	******	*****
Pin #13 020	54 Pol	- 02126	Ac1 x
01536 -x			
01568 xxxxx	******	******	*****

01600	***************************************
01632	***************************************
01664	***************************************
01696	***************************************
01728	***************************************
01760	***************************************
Pin #12	2 02055 Pol - 02127 Acl x
01792	x
01824	***************************************
01856	***************************************
01888	***************************************
01920	***************************************
01952	***************************************
01984	***************************************
02016	***************************************

Example of CUPL Source for Table Entry.

To enter a table of (say) three inputs and six outputs we can use CUPL syntax TABLE.

```
First, define the input and output variable vectors using the syntax of FIELD and
then use the syntax of TABLE to assign the values:
/* Inputs */
PIN 1 = a;
PIN 2 = b;
PIN 3 = c;
/* Outputs */
PIN 12 = u;
PIN 13 = v;
PIN 14 = w;
PIN 15 = x;
PIN 16 = y;
PIN 17 = z;
/* Define multi-bit variables for the input and the output */
FIELD my_inputs [ a, b, c];
FIELD my_outputs [u, v, w, x, y, z];
/* Assign output values to input values */
TABLE my_inputs => my_outputs {
[0, 0, 0] => [1, 0, 1, 1, 0, 0];
[0, 0, 1] \Rightarrow [1, 1, 1, 1, 0, 1];
[0, 1, 0] \Rightarrow [1, 1, 1, 1, 0, 0];
 \begin{bmatrix} 0, 1, 1 \end{bmatrix} \implies \begin{bmatrix} 1, 0, 1, 1, 0, 0 \end{bmatrix}; \\ \begin{bmatrix} 1, 0, 0 \end{bmatrix} \implies \begin{bmatrix} 1, 0, 0, 0, 0, 0 \end{bmatrix}; 
/* and more entries if required */
}
```

PALs for Sequential Logic Design.

To implement sequential circuits the so called registered PALs are available. These have the output OR gates connected to internal flip flops. For example the PAL 16R8 is the registered version of the logic PAL 16L8. The main difference is that the six bidirectional outputs of 16L8 are routed through six separate D-flip flops. The clock input is preassigned to a specific input pin (pin 1 on 16R6) that cannot be used for other purposes.

GAL 16V8 - OMCL

Logic and registered PALs are job specific PLDs and are normally OTPs (one time programmable) only. The so called GAL devices feature CMOS re-programmable fuses so there is no practical limitation on the number of times they can be re-programmed. In addition, the GAL devices have another very useful feature. They can be programmatically configured to behave as PALs of various degrees of complexity. This is achieved by them having the so called Output Logic Macro Cell (OMCL) that can be configured to one of the three device modes: simple, complex and registered. An example of a OMCL used is shown above. The configuration of the OMCL is determined by the fuses that control the inputs to the three multiplexers. In simple and complex modes 16V8 acts as a logic PAL by-passing the D flip flops. The simple mode allows no loop back. In registered mode 16V8 behaves as a registered PAL 16R8.

Explanations of some of the PLD Acronyms.

JEDEC File	A standardized format file containing the fuse map. The file is downloaded to the PLD during the programming cycle.
ОТР	One Time Programmable PLD. The fuse map once programmed cannot be changed.
EP PLD	Electrically Programmable PLD. The fuse map can be deleted by exposing the PLD to UV light. The PLD then can be reprogrammed.
EEP PLD	Electrically Erasable Programmable PLD. The fuse map can be deleted electrically. The PLD then can be re-programmed.
Register PAL	A PAL (such as 18R) where the outputs of OR gates are connected to D flip flops. Register PALs can be used for sequential logic design.
OLMC	The Output Logic Macro Cell. An output sub-circuit of a PAL which can be programmed to act either as a combinatorial or register PAL.
GAL	Generic Array Logic, the term used for EEP PAL having OLMC outputs.
CPLD	Complex PLD. Several hundred PLDs on a single chip with programmable interconnections.
FPGA	Field Programmable Gate Arrays. Contains a very large number of EEP cells. Each cell can typically contain a small PROM, a register and some gates. The interconnections between cells are also programmable.



